

16.2

✓ 300

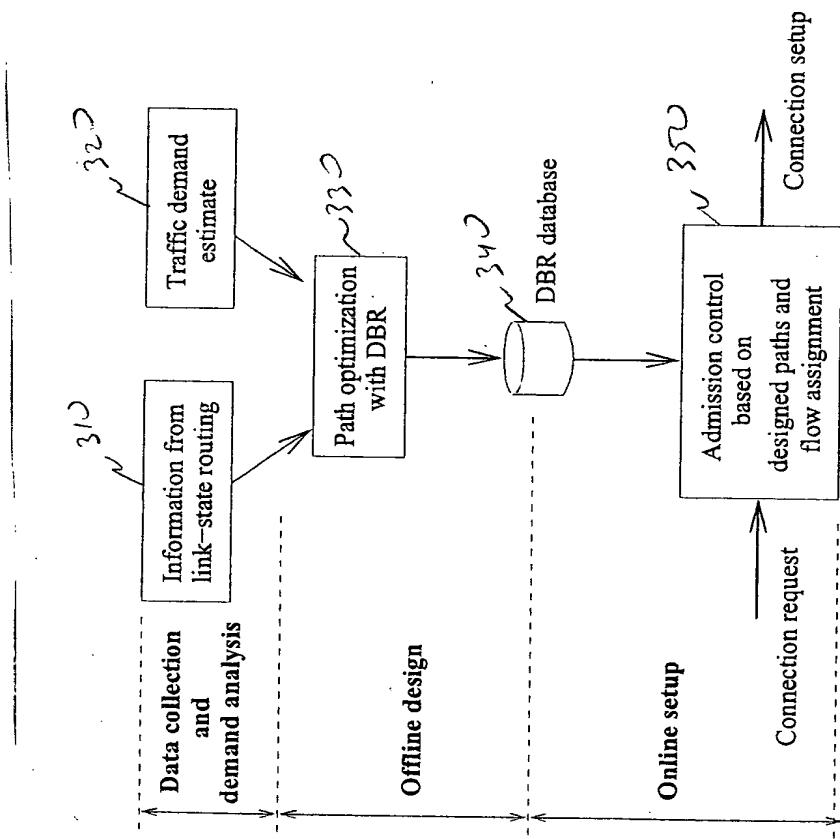


Fig. 3

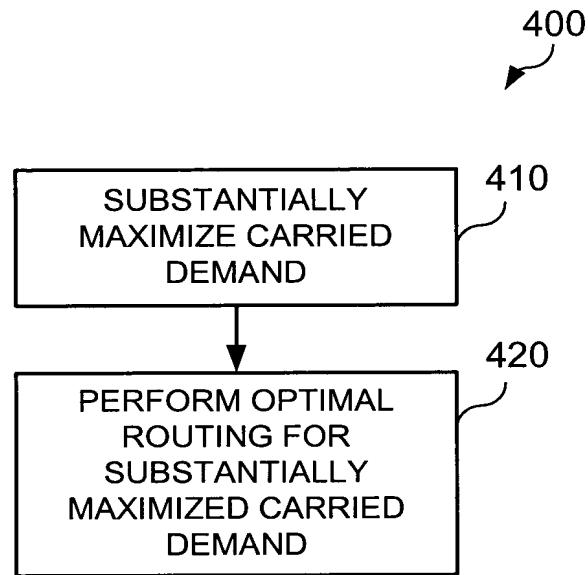
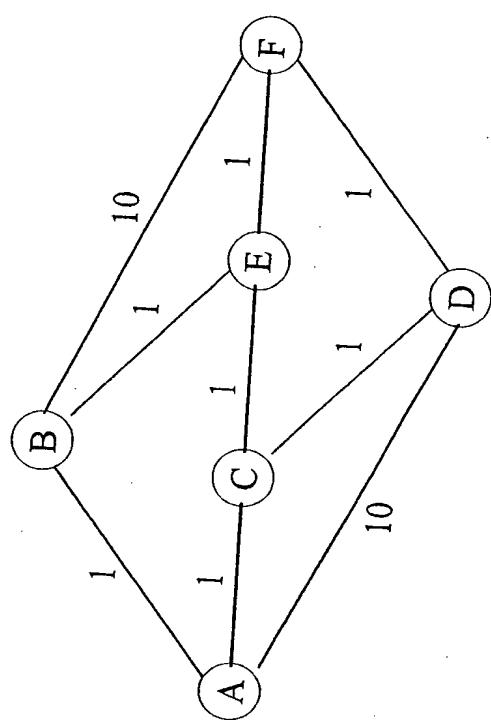


FIG. 4

Fig. 5



```
Adaptive DBR:  
if  $v_{sd} - \hat{v}_{sd}(t) > 0$   
    prune with TR=0  
    if a DBR path exists  
        setup the DBR connection  
    else  
        prune with TR=r  
        compute shortest path on the pruned network  
        setup the connection if possible  
else  
    prune with TR=r  
    if a DBR path exists  
        setup the DBR connection  
    else  
        prune with TR=r  
        compute shortest path on the pruned network  
        setup the connection if possible
```

F16.6

CSPF_TR:
prune with TR=0
compute shortest path on the pruned network
if the resulting path length = $l_{min}(s, d)$
 setup the connection
else
 prune with TR=r
 compute shortest path on the pruned network
 setup the connection if possible

F16.7